





# ELABORAZIONE DI IMMAGINI SATELLITARI TRAMITE TECNICHE DI DEEP LEARNING PER IL MONITORAGGIO DI AREE AMBIENTALI

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# Outline

- Introduction to Remote Sensing
- Database
  - Sentinel-2 Database for Land Cover Classification
- Procedure for automatic classification of Sentinel-2 images
  - Instance Selection
- Results
  - > Pixel-wise Land Cover Classification (SVM & RF)
- Partnership with Planetek



# Introduction to Remote Sensing

### **Remote Sensing (RS)**:

the acquisition of information about a region of interest without any physical contact

## **Social and Economic Impact of RS:**

- Crop production forecast
- Environmental monitoring
- Management of hazards
- Population estimates

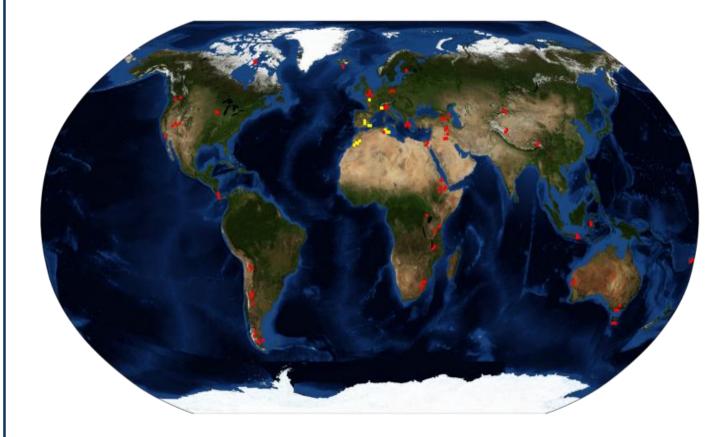








# Sentinel-2 Database for Land Cover Classification



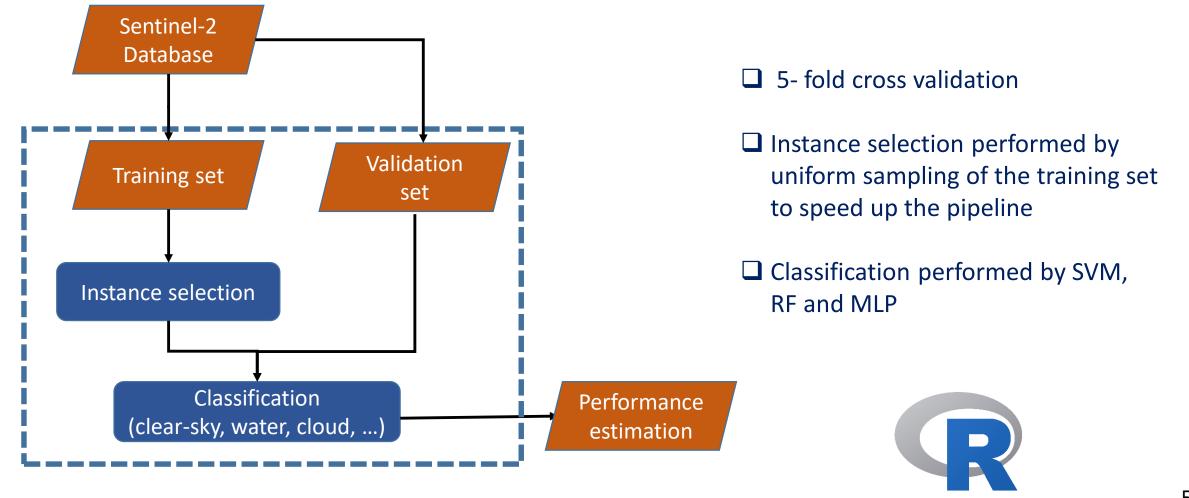
- 108 Sentinel-2 L1C TOA reflectance images
- □ ~ 5 million hand labelled pixels
- □ ~ 30 countries

### □ Six Semantic labels

- Clear sky
- > Water
- Shadow
- > Cirrus
- Cloud
- Snow



# Procedure for automatic classification of satellite optical images



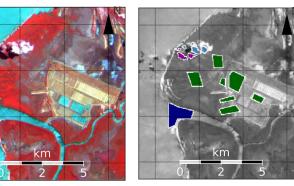


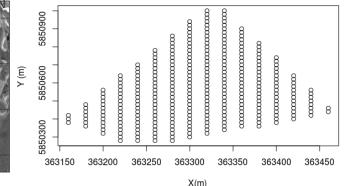
# Instance Selection – Motivation

- The database consists of pixels characterized by highly correlated reflectance spectra by construction as can be show by Moran's Index\*
- Spatial autocorrelation statistics like Moran's I measure the degree if dependency among observation of a certain feature in a geographic space\*

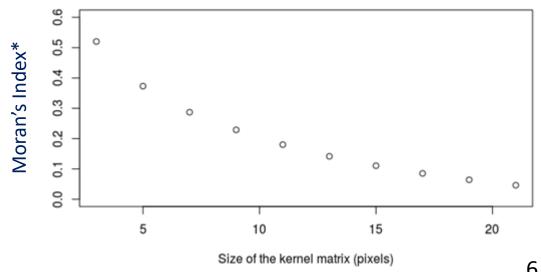
$$I_m = \frac{n}{\sum_i \sum_j w_{ij}} \frac{\sum_i \sum_j w_{ij} (x_i - \bar{x}) (x_j - \bar{x})}{\sum_i (x_i - \bar{x})^2}$$

 $0 < I_m < 1$ , positive correlation





Moran Index vs size of Neighbourhood (feature B2)

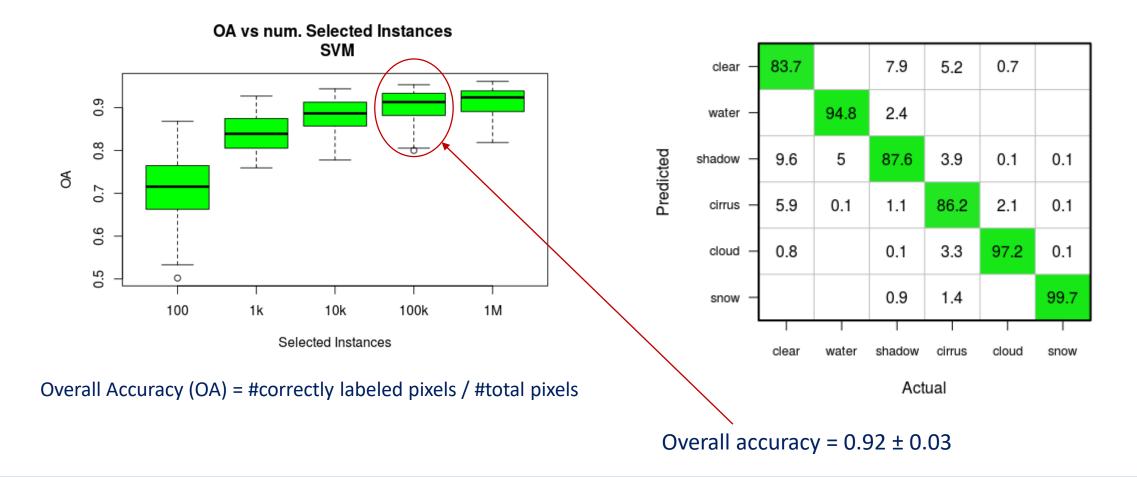


\*Moran, P.A.P. (1950), "Notes on Continuous Stochastic Phenomena" Biometrika, Volume 37, Issue 1-2.



# Land Cover Classification – SVM

## Each pixel is described by 13 reflectance spectra

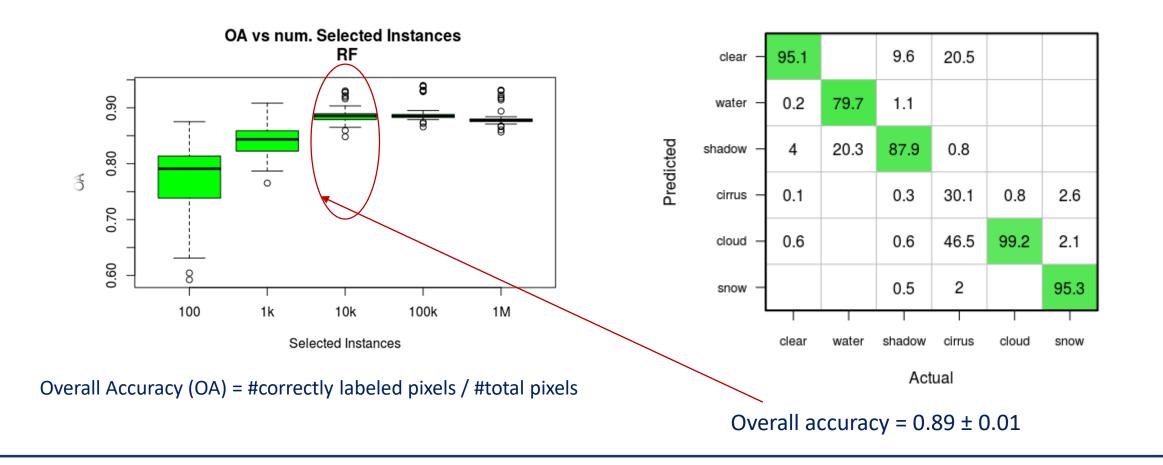


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# Land Cover Classification – RF

## Each pixel is described by 13 reflectance spectra



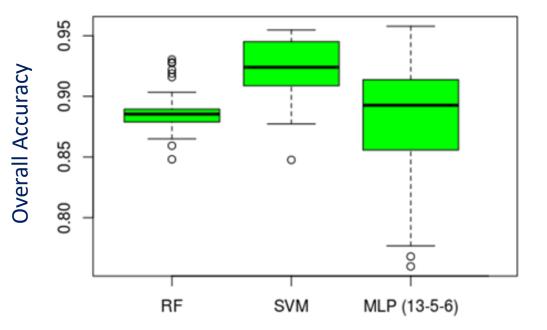
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# LC Classification – Comparison between classifiers

**Overall Accuracy** 

MLP: 0.88 ± 0.04 RF: 0.89 ± 0.01 SVM: 0.92 ± 0.03





# **Conclusions and Future Developments**

## Conclusions

- $\checkmark\,$  SVM is the most accurate classifier
- ✓ RF is the most robust classifier
- $\checkmark\,$  RF is most effective in detecting clear-sky and cloud pixels
- ✓ SVM is most effective in detecting snow, water and cirrus pixels

## Future developments

- Ensemble Classifier
- Deep Learning Techniques (based on DBN or DNN)



# Partnership with Planetek

## Partnership with Planetek

 Development of a procedure to automatically detect buildings in very high resolution satellite images of urban areas Change detection of Build-up areas exploiting multiple classification approaches in VHR images

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DRGANIZATIONS: : DIPARTIMENTO INTERATENEO DI FISICA "M. MERLIN", UNIVERSITA' DEGLI STUDI DI BARI ALDO MORO, BARI, ITAL' : PLANETEK ITALIA S.R.L., ITALY : LABORATORY OF REMOTE SENSING, NATIONAL UNIVERSITY OF ATHENS, ATHENS, GREECE



planetek

## Conferences

 The ESA Earth Observation Φ-week Open Science and Future EO, Frascati, ESRIN, 12-16/11/2018 (poster)





# **Exams and Seminaries**

## PhD Courses

- How to prepare a technical speech in English
- Management and knowledge of european research and promotion of research results
- ✓ Programming with Python for Data Science
- ✓ Image and Signal Processing
- ✓ Introduction to Parallel Computing and GPU Programming using CUDA
- ✓ Interpolation Methods and Techniques for Experimental Data Analysis
- × Introduction to C++ programming

## Seminaries

 "Cycle of lectures on SM and BSM models". Bari, Dipartimento Interateneo di Fisica, Prof. S Khalil - Director of the Center for Theoretical Physics Zewail City for Science and Technology, Egypt. 20-23/03/2018



# Thank you for your attention !



# Any Questions?

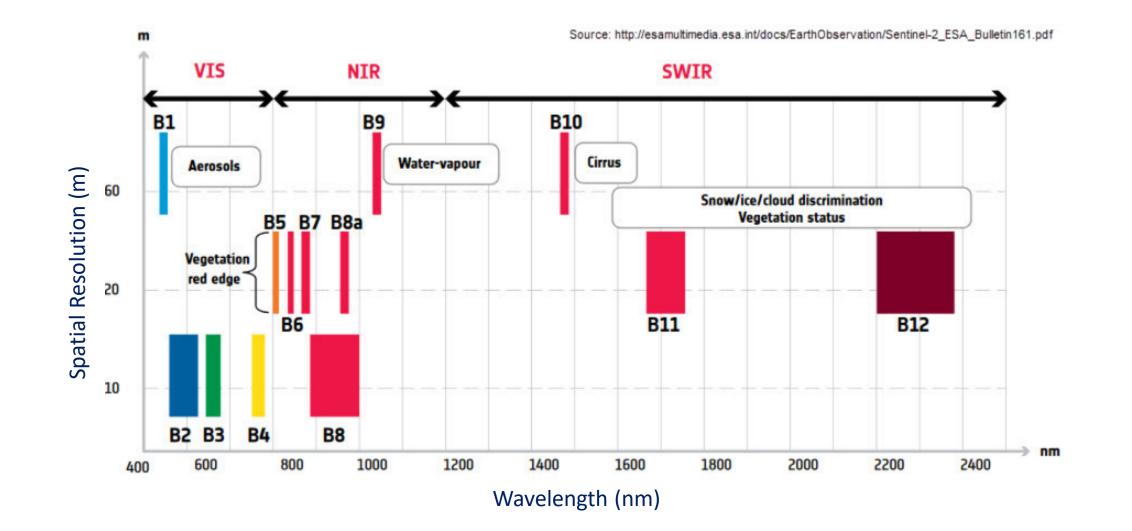




# **Backup Slides**



# Sensors on board Sentinel-2 Satellites





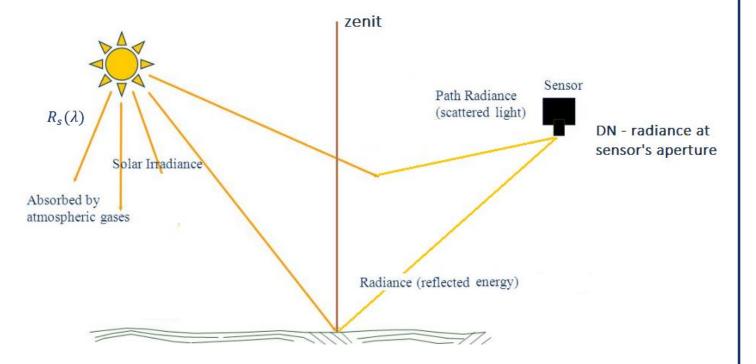
# **Recovery of TOA reflectances**

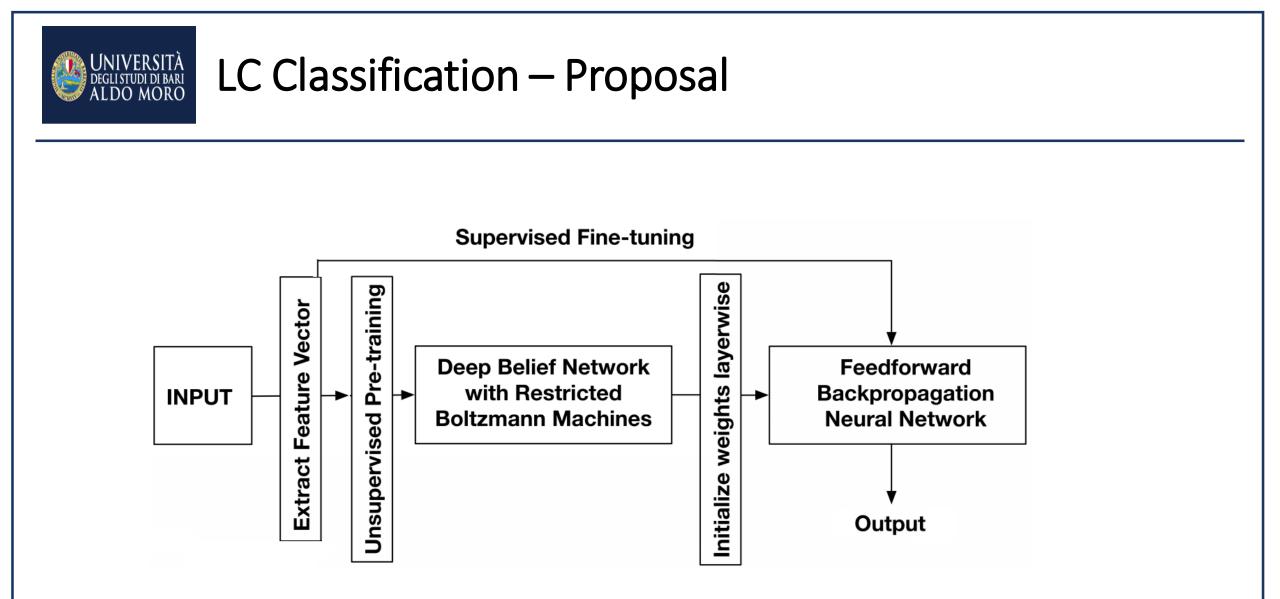
• Recovery of Top-of-atmosphere reflectance  $\rho_k$ 

$$p_k(i,j) = \frac{\pi \times DN(i,j)}{A_k \times E_{s,k} \times \cos(\theta_s(i,j))} \times d(t)$$

With

- *A<sub>k</sub>* calibration coefficient
- $E_{s,k} = \int d\lambda T_k(\lambda) R_s(\lambda)$  extra-terrestrial solar spectrum
- *DN*(*i*, *j*) radiance at sensor's aperture (i.e. radiance leaving the ground \* transmission factor + path radiance)
- $\theta_s(i,j)$  sun zenit angle
- $d(t) = (1 \varepsilon \times \cos(\omega(t 2)))^2$ correction for the sun-Earth distance variation





\*Hinton G.E., et al. "A fast learning algorithm for deep belief nets". Neural computation, 2006 - MIT Press